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Handwritten Signature Recognition Using Neural Networks

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Abstract— This article demonstrates how adaptable neural networks may be used to preprocess handwritten signatures. After interpolating an input signature, a descriptor vector is created to alter the inclination angle. Neurons that are critical for recognition and categorization are preprocessed in a suggested adaptable neural network design. In this study, we present an upgrade to the material-based technique called pseudo coloring. Filling and sharpening color layers on top of the picture is made easier with the addition of edge detection algorithms. For our demonstrations, we use genuine X-ray data from a professional dual energy scanner.

INTRODUCTION

Scanners that use X-RAY technology produce pictures depending on the radiation absorption of different materials. For example, scanners are employed in medical tomography and security. Images produced by this process are often shown in grayscale, with the more absorbent regions being white and the transparent ones being

black. Many people use the inverted version of this color space. This style of presentation, in certain cases, is sufficient for well-trained personnel, but the need to provide additional information to photographs necessitates the inclusion of markings.

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A linear color map is a frequent strategy. In the case of [1] and [2,] it is possible to fivefold boost the depth resolution of images by using an artificial colored cube helix. Using mass attenuation coefficient, more sophisticated algorithms may categorize scanned objects or their components as belonging to one of several materials. Based on the material's atomic number, this coefficient is calculated. On the face of it, this method should allow us to categorise the item according to its atomic number, however testing have shown that objects' thickness plays an important role in this. Using a fire extinguisher as an example, this impact may be readily seen. Computational intelligence (CI) techniques such as pattern analysis and classification have a wide range of applications. Classifying handwritten texts in identity control systems such as branch institutions and remote document verification systems is critical. Dispersed systems require efficient techniques for the collection and retrieval of knowledge. For example, in the situation of missing or partial data [1], [2], and authorship semantic identification [3], many approaches of CI aid. To extract prescriptions and compose robot instructions from normal behavior, the use of Natural Language Processing (NLP) methods might be beneficial. These sorts of systems can benefit from the usage of neural networks (NNs), which are structures that can generalize knowledge in creative systems [6, 7], have a wide range of established designs with new capabilities for multi-agent systems [8, 9], and have more efficient memory.

A. Related Works

We are constantly confronted with

technology as a result of rapid technological advancement. Therefore, the level of security needed to secure our digital data and our identity must be raised to ensure that both are protected. Specific information about the individual or the verification of particular attributes can be used to verify their identity. When it comes to our physical attributes, such as fingerprints, we're all one-of-a-kind.

1. METHODOLOGY

[3] The components of an X-ray inspection system are the detector and the conveyor belt. [3] X-rays are electromagnetic radiation waves that are extremely short in wavelength (0.01-10 nm). See [4] for a range of X-ray photon energies: 30–200 keV. Detectors arranged in an L-shape bar measure the photons that successfully traversed a scanned item.

The two approaches utilized for signature verification are off-line and on-line. One of the most common methods for verifying signatures is to use photographs or a scan of the relevant document. The signature curve can then be assessed once all noise has been removed. After a period of time, these approaches can be used to study graphology or verify the authenticity of a signature. If you're looking for certain qualities like rounding or distortion, you can use these approaches. [12] Secondly, there are online signatures, which are signatures made at the moment of analysis. The curve and its properties aren't the only things to take into account. Other elements include pen pressure, angle of inclination, typing speed, or even how long it takes to raise the pen from the page. It is possible to extract data from a live signature in various ways, and the majority of these methods are being improved all the time. To normalize length, up- and down-sampling can be used, as can a vertical partitioning curve (see references

13 and 14). Other approaches to the problem are shown in [15], in which the authors demonstrate how to extract features based on a combination of gray-level information, signature size, and radian. A classifier must be used to identify the trademark qualities.

Classifiers based on statistical analysis and neural networks are the most frequent, although there are others. Another technique for training neural networks using signature characteristics is shown in [17], while a new approach utilizing probabilistic neural networks and hybrid discrete random transform, principal component analysis approaches is described and demonstrated in [18]. Narrowing the amount of samples utilized to train a neural network is a key challenge in neural network application. It's impossible to imagine a circumstance where the employer wants his staff to sign hundreds of documents.

A. Hardware

Dual energy range detectors allow us to concurrently take two X-ray images from a single monoblock source. This means that we acquire two sets of data in a single X-ray exposure for two images (low and high energy, LE and HE respectively). The detector's design includes a number of moving elements. CsI (300mg/cm²) and CsI (153mg/cm²) are the two most often used scintillators (TI). The first one measures in at 3.0 mm in thickness, while the second one measures in at 4.1 mm. In addition, a filter (0.6 mm copper) separates the LE and HE scintillators, enhancing performance even further. A tube using a 160 keV voltage and a 5300A current generates our X-ray images, and detectors track the rays after they've gone through the scanned objects. Experimentally, we're

working with tube models XRB160P and 1,553 DE-ENET detectors from X-Scan (model 1,5L-1253).

Moving objects at a speed rate of 40 cm/second was used in the testing process. Scannable items can be as wide as 1000 mm or as long as the user desires because they can be moved horizontally.

I. HANDWRITTEN CURVE TRANSFORMATION

Authenticating the signatures of users is a difficult challenge. We all have a unique way of writing. It is possible for the signature to be deformed if we sign too rapidly or jerkily. There is a specified area in electronic systems where the positioning or rotation of an input curve may pose complications for DSS (Digital Signature Service). Although the user should be allowed to write freely, the created solution should be responsible for accurately identifying the input curve and cutting, rotating or resizing it as needed for recognition purposes. We are the object in the suggested solution, where the handwritten curve is interpolated.

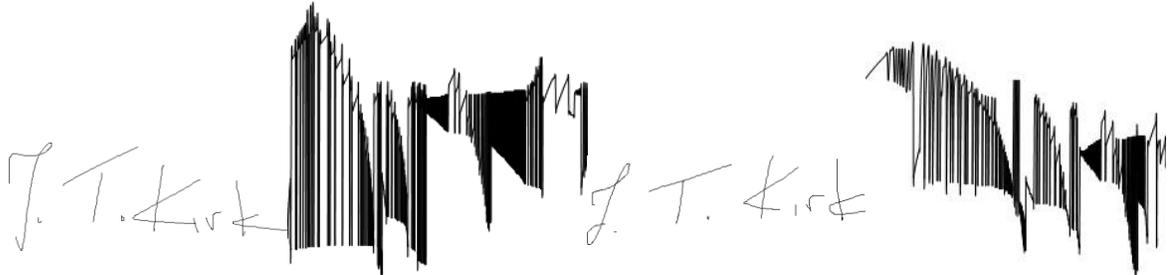
Quantity (Q) is determined by dividing an object's material value by a logarithm of that value (see Eq. 9). Based on industry requirements for professional security scanners, Three materials were chosen based on their Q values:

Low- and high-pass filters are used to distinguish between pixels that can be seen by X-rays and those that can't. In order to get these numbers, we had to conduct an experiment. Depending on the scanner, these numbers might be varied depending on the machine. Our three binary representations now represent all of the different range of materials (see Fig. 4).

A. Mask Enhancement

Because of the high resolution and huge number of discrete pixels in these photos, they are known as "high-quality images." Using a morphological filling or blurring, this problem can be resolved. As a first step in post-processing, we apply a simple

Gaussian blur to these images. 7 7 and 5 5 are the best values for the Gaussian filter masks. It is impossible to cover all the holes in the object with a 3 3 mask, whereas larger masks have little effect on the final picture while increasing computing complexity.



A classifier based on neural networks is shown in Figure 2. As an input item, we can see a handwritten curve that has been interpolated using the Chebyshev method before being passed on to the flexible neural network design. A point's connection with a certain mask

was determined using a voting mechanism. It is necessary to multiply the previously used Gaussian filter mask by the current pixel size in order to produce an area of interest that is larger than this. On Fig. 6, an example is provided.

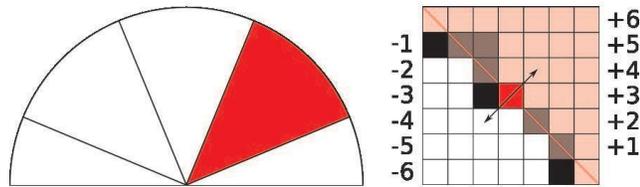


Fig. 6. A pixel with a 45 22.5 contrast gradient degree and a 7 7 Gaussian mask is shown in this example.

Using the Canny technique, we can identify a boundary by its black pixels. Border points are being processed in the current phase, and the red pixel in the center is one of them. This red pixel must be placed at an angle of 45 22.5 degrees with respect to two neighbouring pixels to the southwest and northeast, which are connected by the arrowed line in the image below (see Fig. 6b). Fig. 7b shows a blurred binary picture of two pixels, and the values of those pixels are read and compared to determine which one is bigger. It all depends on how much of an angle in the square you can cut out using a

line perpendicular to the discretized gradient (D). In our illustration, shown in Fig. 6b, this line is highlighted in red. In this example, the triangle (or rectangle) containing the higher-valued pixel is designated as the foreground, while its lower-valued counterpart is designated as the background. Using a transparent red color, the foreground triangle is shown. You may create a "affiliation matrix" based on these values to determine which pixels are part of the material layer and which are not. Size of affiliation matrix acquired picture is same to matrix Only those pixels

that were successfully blurred are processed in this manner (see 7c).

The program then fills in the affiliation mask with the correct values. It's possible to map the highest-valued pixels in a picture to the highest-valued pixels on the affiliation mask, as shown in Figure 7b. The association mask will convert every pixel with a 0 value to a minimally negative value. For the rest of the pixels, we've set their values to 0. (Shown in a gray in Fig. 7b). Using the Canny edge vector, the affiliation mask must be specified for each pixel. Currently, the Canny edge vector pixel coordinates are used to center this region. Previous step's Gaussian mask has the same size as this area. In the zone of interest, each foreground pixel receives a positive value addition.

There are certain pixels that correspond to many material layers at this phase in the study. The studied pixel must be allocated to one of the following layers: Pixels from the same locations on distinct material layers are compared to see if they are affiliated with each other using a voting method. It's possible for a pixel to have the highest value on one mask while the identical pixel's value is set to zero on the other masks. Affiliated pixels are now identified by a mask that indicates whether or not they are part of the given layer. In order to get a threshold value greater than zero, this mask was binarized. Fig. 7b shows a blurred image that is multiplied by a binary affiliation mask (Fig. 7c). Finally, add a predetermined color to the layer mask.. For metals, orange is commonly used in pseudo colored X-ray imaging, while green is commonly used for biological materials.

B. Histogram Equalization of Background Image

When it comes to layer masks, they all have the same color. An very stark

background is necessary for objects covered by a single layer of substance to be easily apparent. The absence of contrast is clearly obvious in the raw photos depicted in Fig. 3. Using an 8-bit depth resolution for visual evaluation of scanned items is required. Good thing we have pictures captured by our CT scans, which take use of a full 16-bit resolution, which allows us to enhance image quality without sacrificing any critical data.

An examination of the 16-bit grayscale data quickly indicates that just a small percentage of the dynamic range is used to store important information. To broaden the usable range, we apply histogram normalization. When the histogram is stretched to use the complete grayscale space range, the contrast improves See [9] for further information.

A simple treshold may enhance an image. As the arithmetic mean of pixel values in the background, the threshold level is arrived at. There are four corners of the picture where the arithmetic mean is computed. A 90% background level should be used when there is more than a 10% variance in mean values between the four corners. (The 230 result, for example, is obtained with an 8-bit depth). This number usually suffices to eliminate all of the unwanted noise. Figure 8c shows the final outcome.

See [10] CLAHE (Contrast-Limited Adaptive Histogram Equalization) is a technique that may be used to increase the contrast of a photograph. To create a thresholded backdrop, you'll need to apply this algorithm. In areas with a lot of contrast, the CLAHE algorithm reduces the histogram's peak height. The algorithm boosts contrast in areas with poor contrast. Because in our scenario, this method does not minimize information, the essential

phases of the Enhanced Color Algorithm are as follows:

- 1) Obtain X-ray pictures with high and low energies.
- 2) The Canny method may be used to find the binary edges of the high-energy picture..
- 3) You may save Canny algorithm co-product values of gradient angles.
- 4) Every pixel's HE/LE logarithmized ratio should be obtained.
- 5) *Images for each material range should be created in binary form*
- 6) Each binary picture has a unique identifier
 - a) Blur an image with a Gaussian filter mask of either 5 5 or 7 7.
 - b) Create a binary image-sized affiliation mask.
 - c) For each egde pixel (found in second step):
 - i) Determine the area of interest on the affiliation mask centered at the current edge point.
 - ii) The gradient angle of a line is used to compare two pixels that are located next to each other.
 - iii) Set perpendicular to this dividing line between the foreground and the background of its neighborhood
 - iv) For each pixel in the focus area:
Foreground pixels are those that are visible while looking at

the display.

otherwise, pixel

values are added:

from the pixel's affiliation values

- 7) Pixels with the highest possible values are selected for affiliation masks..
- 8) The masks of affiliation should be consolidated into a single entity.
- 9) For each binary image:
 - a) An affiliation mask can be applied to a Gaussian blurred binary picture.
 - b) Defining the final color layer
- 10) Normalize the contrast of images with a high level of intensity.
- 11) Increase or decrease the image's sensitivity
- 12) CLAHE is applied to the final backdrop image.
- 13) Place each material layer on top of the backdrop picture.

It's a challenging task to verify the authenticity of user signatures. Each of us has an own style of writing. It is possible for the signature to be deformed if we sign too rapidly or jerkily. There is a specified region in electronic systems where the location or rotation of an input curve may pose challenges for DSS systems. However, the user should be able to write freely and the created solution should be responsible for accurately detecting the input curve and cutting, rotating, and resizing it if necessary for recognition purposes. Using our proposed approach, we transform the signature curve from 530 270 pixels to 40*15 pixels processed objects. It is said that a transformation has taken place when an original handwritten curve is converted to an interpolated shape.

If the edges of the scanned item are smooth or sharp, the method provided has the capacity to discriminate between material layers. The technique provided here may be used to examine any number of layers. We must keep in mind that inspectors might become disoriented when confronted with more than four distinct color palettes when screening luggage.

A quadratic dependence between the number of edge pixels in a layer and the algorithm's time complexity means that it is extremely fast. An Intel Core i5-3470 3.2 GHz processor powers our test computer and executes the procedure shown in real time. A single scan picture with a resolution of 1024 by 1024 pixels takes between one and three seconds to process for most scanned objects. As a result, scans are processed in a fraction of the time normally required by the scanner. Therefore, these units are determining whether or not the signature is authenticated.

When compared to a traditional approach, the proposed architecture obtained a 17 percent improvement in original signature accuracy and a 26 percent increase in fake signature accuracy. To assist the training process reach the target error value faster, impact coefficients were introduced. Experiment findings suggest that the proposed technique may be easily implemented in user verification systems that employ signature processing. We want to use fuzzy measurements of relevance instead of factors in the future. These improvements will allow for improved recognition of a wider range of signatures while yet maintaining high levels of accuracy.

I. CONCLUSION

With the introduction of the "Arida" scanner driver software, the previously

stated fake coloring technique has already found its way into professional workflows. Other than picture adjustment and object identification, it is being utilized in a variety of applications. Baggage inspectors use a colored X-ray picture as a primary tool.

When the attenuation coefficient is near to known concentrations of drugs or explosives, this approach can be used as a filter to help identify possible dangers. In user verification systems, there are a variety of input devices and resolutions to choose from. In addition, we should expect a wide range of languages and writing styles to be used. In order to identify between genuine and false signatures, the method used must be highly effective. A mathematical approach may be used to change the shape of a person's signature, as it is mathematically a continuous or broken curve. A approach that interpolates input signals into customized objects for flexible neural network DSS has been proposed as a result of this.

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